A Geometric Proof of the Jordan Canonical Form of a matrix A

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Let A be an $n \times n$ matrix. We say that u is an eigenvector corresponding to the eigenvalue λ if

$$(A - \lambda I)u = 0.$$

We way u is a generalized eigenvector if there exists $N > 1$ such that

$$(A - \lambda I)^N u = 0.$$

We want to show that there exists a basis of n generalized eigenvectors

$$P = (u_1, \ldots, u_n)$$

such that

$$P^{-1}AP = \mathrm{diag}(B_i),$$

where B_i is a square matrix of the form

$$B_i = \begin{pmatrix} \lambda_i & 1 & 0 \ldots 0 \\ 0 & \lambda_i & 1 \ldots 0 \\ 0 & \ldots & \lambda_i \ldots 1 \\ 0 & 0 & 0 \ldots \lambda_i \end{pmatrix} = \mathrm{diag}(\lambda_i) + N_i.$$

The matrix N_i is nilpotent. See:
http://en.wikipedia.org/wiki/Nilpotent_matrix

The proof is divided into several lemmas, which are of independent interest.

For each $\lambda \in \mathbb{C}$, let $A_\lambda = A - \lambda I$. Let $X = \mathbb{C}^n$.

Lemma 0.1.

$$X \supset R(A_\lambda) \supset \cdots \supset R(A_\lambda^k) \supset R(A_\lambda^{k+1}),$$
$$R(A_\lambda^{k+1}) = A_\lambda R(A_\lambda^k)$$

Lemma 0.2.

$$0 \in N(A_\lambda) \subset N(A_\lambda^2) \subset \cdots \subset N(A_\lambda^k) \subset N(A_\lambda^{k+1}),$$
$$N(A_\lambda^{k+1}) = A_\lambda^{-1} N(A_\lambda^k),$$

where A_λ^{-1} denotes the pre-image of the mapping A_λ.

Definition 0.3. *There exists $k \geq 0$ such that $N(A_\lambda^k) = N(A_\lambda^{k+1})$. The smallest such number is called the ascent of A_λ, and is denoted by $\alpha(A_\lambda)$.*

There exists $k \geq 0$ such that $R(A_\lambda^k) = R(A_\lambda^{k+1})$. The smallest such number is called the descent of A_λ, and is denoted by $\delta(A_\lambda)$.

Remark 0.4. *(1) If $\alpha(A_\lambda) = 0$, then A_λ is nonsingular. If $\delta(A_\lambda) = 0$, then $R(A_\lambda) = X$. Again A_λ is nonsingular. Thus, $\alpha(A_\lambda) = 0$ is equivalent to $\delta(A_\lambda) = 0$.*

(2) $R(A_\lambda^k) = R(A_\lambda^{k+1})$ for all $k \geq \delta(A_\lambda)$. Similarly $N(A_\lambda^k) = N(A_\lambda^{k+1})$ for all $k \geq \alpha(A_\lambda)$.

Lemma 0.5. *$\alpha := \alpha(A_\lambda) = \delta := \delta(A_\lambda)$.*

Proof. The proof is divided into two parts:

(1) Show $\alpha \leq \delta$.

Since $N(A_\lambda^{\alpha-1}) \neq N(A_\lambda^\alpha)$, there exists $x_0 \in N(A_\lambda^\alpha)$ but $x_0 \neq N(A_\lambda^{\alpha-1})$. Thus, $y = A_\lambda^{\alpha-1}x_0 \neq 0$ but $A_\lambda^\alpha x_0 = 0$. This shows that $\dim R(A_\lambda^\alpha) < \dim R(A_\lambda^{\alpha-1})$. Thus $R(A_\lambda^{\alpha-1}) \neq R(A_\lambda^\alpha)$. Therefore $\delta(A_\lambda) \geq \alpha(A_\lambda)$.

(2) Show $\delta \leq \alpha$.

Since $R(A_\lambda^{\delta-1}) \neq R(A_\lambda^\delta)$, there exists $y \in R(A_\lambda^{\delta-1}), y \neq 0$ but $A_\lambda y = 0$. Let $y = A_\lambda^{\delta-1}x_0$. Then $A_\lambda^{\delta-1}x_0 \neq 0$ but $A_\lambda^\delta x_0 = 0$. This shows that $N(A_\lambda^{\delta-1}) \neq N(A_\lambda^\delta)$. Therefore $\alpha(A_\lambda) \geq \delta(A_\lambda)$. □

Lemma 0.6. *Let λ be an eigenvalue of A, and $p := \alpha(A_\lambda) = \delta(A_\lambda)$. Then:*
(1) The matrix A_λ is nonsingular in $R(A_\lambda^p)$.
(2) Let $\mu \neq \lambda$. Then the matrix A_μ is nonsingular in $N(A_\lambda^p)$.

Proof. (1) If there exists $x \in R(A_\lambda^p)$ such that $A_\lambda x = 0$, then $A_\lambda R(A_\lambda^p) \neq R(A_\lambda^p)$, contradicting to $p = \delta(A_\lambda)$.

(2) Assume that there exists $x \in N(A_\lambda^p)$ such that $A_\mu x = 0$. Since $x \in N(A_\lambda^p)$, there exists an integer $k \geq 0$ such that $A_\lambda^{k-1}x \neq 0$, $A_\lambda^k x = 0$. Applying A_λ^{k-1} to

$$A_\lambda x + (\lambda - \mu)x = 0,$$

we have $(\lambda - \mu)A_\lambda^{k-1}x = 0$. This can occur only if $\lambda - \mu = 0$. □

Our next man result shows that X is a direct sum of two invariant subspaces $R(A_\lambda^p) \oplus N(A_\lambda^p) = X$, where λ is nonsingular on $R(A_\lambda^p)$ and λ is the only eigenvalue for $N(A_\lambda^p)$.

Lemma 0.7. *Let $p = \alpha(A_\lambda) = \delta(A_\lambda)$. Then*

$$R(A_\lambda^p) \oplus N(A_\lambda^p) = X.$$

Proof. (1) We show that $R(A_\lambda^p) \cap N(A_\lambda^p) = 0$.
If $y \in R(A_\lambda^p) \cap N(A_\lambda^p)$, then $y = A_\lambda^p x$ and $A_\lambda^p y = 0$. Thus $A_\lambda^{2p} x = 0$. $x \in N(A_\lambda^{2p}) = N(A_\lambda^p)$. Thus $A_\lambda^p x = 0$. This implies $y = 0$.

(2) We show that for any $x \in X$, there exist $x_1 \in R(A_\lambda^p),\ x_2 \in N(A_\lambda^p)$ such that $x = x_1 + x_2$.

Consider $A_\lambda^p x \in R(A_\lambda^p) = R(A_\lambda^{2p})$. There exists y such that $A_\lambda^{2p} y = A_\lambda^p x$. Thus

$$A_\lambda^p (x - A_\lambda^p y) = 0.$$

Let $x_1 = A_\lambda^p y$, and $x_2 = x - x_1$. Then $x_1 \in R(A_\lambda^p),\ x_2 \in N(A_\lambda^p)$. □

Let

$$\lambda_1, \dots, \lambda_m$$

be a list of all the distinct eigenvalues of A, each associated with a unique

$$p_i = \alpha(A_{\lambda_i}) = \delta(A_{\lambda_i}).$$

We have shown

$$R(A_{\lambda_i}^{p_i}) \oplus N(A_{\lambda_i}^{p_i}) = X.$$

Clearly $N(A_{\lambda_i}^{p_i})$ is the generalized eigenspace for λ_i.

We now show

Lemma 0.8.

$$\oplus_i N(A_{\lambda_i}^{p_i}) = X.$$

Proof. (1) We show that the generalized eigenspaces, each corresponding to a distinct λ_i, are linearly independent. Let k be the smallest integer such that $x_1 + \cdots + x_k = 0$ where we assume, without loss of generality, $x_j \in N(A_{\lambda_j}^{p_j})$ and is nonzero.

Applying $A_{\lambda_1}^{p_1}$ to $x_1 + \cdots + x_k = 0$, we have

$$A_{\lambda_1}^{p_1} x_2 + \cdots + A_{\lambda_1}^{p_1} x_k = 0.$$

From Lemma 0.6, $A_{\lambda_1}^{p_1}$ is nonsingular in each of its invariant subspace $N(A_{\lambda_j}^{p_j}), j \neq 1$, and thus $y_j := A_{\lambda_1}^{p_1} x_j \neq 0$. We have $y_2 + \cdots + y_k = 0$. This is a contradiction to the minimal property of k.

(2) For any $x \in X$, we show, by induction, that it is possible to express x as $x = x_1 + \dots x_m$ with $x_i \in N(A_{\lambda_i}^{p^i})$.

If $m = 1$, then $R(A_{\lambda_1}^{p_1}) \oplus N(A_{\lambda_1}^{p_1})$. From Lemma 0.6, λ_1 is not an eigenvalue of A restricted to $R(A_{\lambda_1}^{p_1})$. If $R(A_{\lambda_1}^{p_1}) \neq 0$, then the restriction of A to it has no eigenvalue. This is a contradiction. Thus $R(A_{\lambda_1}^{p_1}) = 0$ and $X = N(A_{\lambda_1}^{p_1})$.

If the lemma is true for $m - 1$, then consider all the invariant subspaces

$$N(A_{\lambda_2}^{p_2}), \dots, N(A_{\lambda_m}^{p_m}).$$

They are all contained in $R(A_{\lambda_1}^{p_1})$ because from Lemma 0.6, A_{λ_1} is nonsingular in each $N(A_{\lambda_j}^{p_j}), j \geq 2$. Therefore, if A is restricted to $R(A_{\lambda_1}^{p_1})$, it has all the eigenvalues $\lambda_2, \ldots, \lambda_m$ but not λ_1. This is due to Lemma 0.6 that λ_1 is not an eigenvalue in $R(A_{\lambda_1}^{p_1})$. Based on the induction assumption, for the case of $m-1$ eigenvalues, we have

$$R(A_{\lambda_1}^{p_1}) = \oplus_{2 \leq j \leq m} N(A_{\lambda_j}^{p_j}).$$

Thus

$$X = \oplus_{1 \leq j \leq m} N(A_{\lambda_j}^{p_j}).$$

□

To finish the construction of the Jordan canonical form, it remains to show that in each generalized eigenspace $N(A_{\lambda_j}^{p_j})$, a cyclic basis can be selected. The idea of the proof is illustrated in Figure 1.

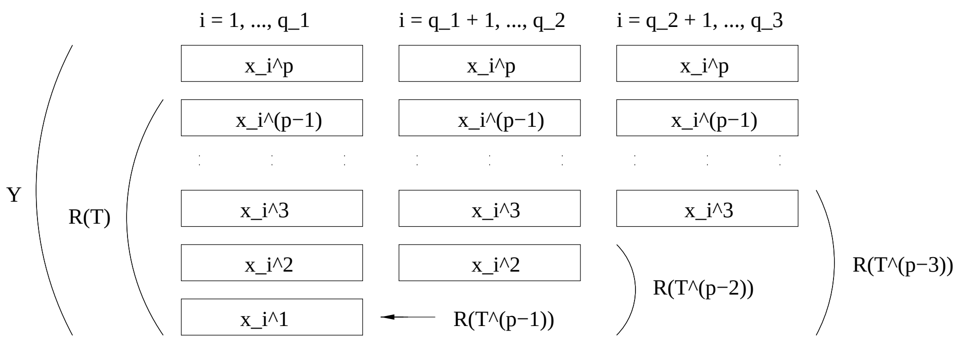

FIGURE 1. A cyclic basis can be selected for $N(A_\lambda^p)$.

Let T be the restriction of the matrix A_λ to $Y := N(A_\lambda^p)$ where λ is one of the λ_j and $p = p_j$. Since $T^p = 0$ but $T^{p-1} \neq 0$, $R(T^{p-1}) \neq 0$. Let $(x_1^1, \ldots, x_{q_1}^1)$ be a basis of $R(T^{p-1})$. Each x_i^1 can be written as $x_i^1 = T^{p-1} x_i^p$ for some $x_i^p \in Y, i = 1, \ldots, q_1$. If $p > 1$, set $T^{p-2} x_i^p = x_i^2$, so that $T x_i^2 = x_i^1$. The vectors $x_i^k, k = 1, 2, i = 1, \ldots, q_1$, belong to $R(T^{p-2})$ and are linearly independent. In fact, $\sum \alpha_i x_i^2 + \sum \beta_i x_i^1 = 0$ implies $\sum \alpha_i x_i^2 = 0$ on applying T and hence $\alpha_i = 0$ for all i, hence $\sum \beta_i x_i^1 = 0$ and $\beta_i = 0$ for all i. We can enlarge the family $\{x_i^k\}$ to a basis of $R(T^{p-2})$ by adding, if necessary, new vectors $x_{q_1+1}^2, \ldots, x_{q_2}^2$; here we can arrange that $T x_i^2 = 0$ for $i > q_1$. (Proof: Consider $T x_i^2, i > q_1$, which are in $R(T^{p-1})$. Therefore $T x_i^2, i > q_1$ can be written as a linear combination of $x_i^1, i = 1, \ldots, q_1$. We then subtracting $x_i^2, i > q_1$, by a linear combination of $x_i^2, i = 1, \ldots, q_1$ with the same coefficients. This yields is a revised set of new vectors which are mapped to 0 by T.)

If $p > 2$, we can repeat the process the same way. Finally, we arrive at a basis $\{x_i^k\}$ of Y with the following properties: $k = 1, \ldots, p, j = 1, \ldots, q_k, q_1 \leq q_2 \leq \cdots \leq q_p$,

$$Tx_j^k = \begin{cases} x_j^{k-1}, & 1 \leq j \leq q_{k-1}, \\ 0, & q_{k-1} + 1 \leq j \leq q_k, \end{cases}$$

where we set $q_0 = 0$.

If we arrange the basis $\{x_j^k\}$ in the order $\{x_1^1, \ldots, x_1^p, x_2^1, \ldots, x_2^p, \ldots\}$, the matrix of T with respect to this basis takes the form

$$\begin{pmatrix}
0 & 1 & & & & & & & & & & & \\
 & 0 & 1 & & & & & & & & & & \\
 & & \cdot & \cdot & & & & & & & & & \\
 & & & \cdot & \cdot & & & & & & & & \\
 & & & & 0 & 1 & & & & & & & \\
 & & & & & 0 & & & & & & & \\
 & & & & & & 0 & 1 & & & & & \\
 & & & & & & & 0 & 1 & & & & \\
 & & & & & & & & \cdot & 1 & & & \\
 & & & & & & & & & 0 & & & \\
 & & & & & & & & & & \cdot & \cdot & \\
 & & & & & & & & & & & \cdot & \cdot
\end{pmatrix}$$

Figures that illustrate the proofs.