

# STURM-LIOUVILLE THEORY, VARIATIONAL APPROACH

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## 1. QUADRATIC FUNCTIONAL AND THE EULER-JACOBI EQUATION

The purpose of this note is to study the Sturm-Liouville problem. We use the variational problem as a tool – minimizing the functional is not the goal of this note.

Consider the quadratic functional

$$(1) \quad K(y) = \int_a^b [P(x)y^2 + R(x)y'^2]dx.$$

The Euler equation is the well-known Jacobi equation

$$(2) \quad Py - \frac{d}{dx}(Ry') = 0.$$

Consider the isoperimetric problem: find the stationary solution for  $K$  with the constrain

$$(3) \quad \int_a^b y^2 dx = 1.$$

The method of multiplier leads to the problem of finding the stationary solution for

$$\int_a^b (Ry'^2 + Py^2 - \lambda y^2)dx.$$

The corresponding Euler equation is

$$(4) \quad Py - \frac{d}{dx}(Ry') = \lambda y.$$

This is so called the Sturm-Liouville equation.

We will only consider the simplest boundary conditions

$$(5) \quad y(a) = y(b) = 0.$$

Assume that  $R(x)$  and  $P(x)$  are  $C^1$  functions, and  $R(x) > 0$  for  $a \leq x \leq b$ .

Introducing the notation

$$(6) \quad L(y) = Py - \frac{d}{dx}(Ry').$$

Jacobi equation (2) and S-L equation (4) become

$$L(y) = 0, \quad L(y) = \lambda y.$$

Usually  $L(y)$  is called the S-L operator. It is linear – for any  $C^2$  functions  $y_1, y_2$  and any constant  $\alpha$ ,

$$\begin{aligned} L(y_1 + y_2) &= L(y_1) + L(y_2), \\ L(\alpha y) &= \alpha L(y). \end{aligned}$$

### Quadratic and bilinear functionals

Define

$$(7) \quad K(y, z) = \int_a^b (Ry'z' + Pyz)dx.$$

$K(y, z)$  is bilinear with respect to  $y = y(x)$  and  $z = z(x)$ . When  $y = z$ , we have

$$K(y, y) = K(y).$$

Observe that

$$\begin{aligned} K(a_1y + a_2z) &= a_1^2K(y) + 2a_1a_2K(y, z) + a_2^2K(z), \\ K\left(\sum_{i=1}^n a_i y_i\right) &= \sum_{i=1}^n a_i^2 K(y_i) + 2 \sum_{j>i} K(y_i, y_j). \end{aligned}$$

Using the boundary condition (5),

$$\int_a^b Ry'z'dx = - \int_a^b \left(\frac{d}{dx}Ry'\right)zdx = - \int_a^b \left(\frac{d}{dx}Rz'\right)ydx.$$

Thus, (7) can be written as

$$(8) \quad K(y, z) = \int_a^b L(y)zdx,$$

where  $L(y)$  is from (6). Obviously we also have

$$K(y, z) = \int_a^b L(z)ydx.$$

Therefore

$$(9) \quad \int_a^b L(y)z dx = \int_a^b L(z)y dx.$$

In particular, if  $y = z$ ,

$$(10) \quad K(y) = \int_a^b L(y)y dx.$$

**Self-adjoint operators** Assume that a linear operator  $Ay(x)$  is defined on the function space  $\{y(x) : a \leq x \leq b\}$ . If for any functions  $y(x), z(x)$  in the space, we have

$$\int_a^b (Ay)z dx = \int_a^b (Az)y dx,$$

then  $Ay$  is called a self-adjoint operator. Equation (9) shows that the S-L operator is self-adjoint.

Similarly, we can show that in the space  $y \in C^1$ ,  $L(y)$  is self-adjoint under the conditions

$$y'(a) = 0, \quad y'(b) = 0.$$

Also, the operator  $L(y)$  is self-adjoint under the periodic boundary condition with period  $\omega = b - a$ :

$$y(b) = y(a), \quad y'(b) = y'(a).$$

**Orthogonality:** Two functions  $y_1(x)$  and  $y_2(x)$  are orthogonal on  $[a, b]$  with respect to the weight  $\rho(x)$  if

$$\int_a^b \rho(x)y_1(x)y_2(x) dx = 0.$$

The function  $y_1(x)$  is said to be normalized with respect to the weight  $\rho(x)$  if

$$\int_a^b \rho(x)y_1^2(x) dx = 1.$$

We assume that  $\rho(x) \geq 0$  and is not identically zero.

A sequence of functions  $y_i$  is said to be orthonormal with respect to  $\rho(x)$  if

$$\int_a^b \rho(x)y_i(x)y_j(x) dx = \begin{cases} 0 & i \neq j, \\ 1 & i = j. \end{cases}$$

## 2. EIGENVALUES AND EIGENFUNCTIONS

For any real or complex  $\lambda$ , equation (4) under condition (5) has a trivial solution

$$y(x) \equiv 0.$$

But for some  $\lambda$ , the system may have nontrivial solution  $y \neq 0$ . Those  $\lambda$  are called eigenvalues of the operator  $L$ , and the corresponding nontrivial functions are called eigenfunctions of  $L(y)$ . The eigenfunction is said to be normalized if

$$\int_a^b y^2(x)dx = 1.$$

**Basic properties of eigenvalues and eigenfunctions**

1. If  $y(x)$  is an eigenfunction with  $y(a) = y(b) = 0$ , then

$$y'(a) \neq 0, \quad y'(b) \neq 0.$$

2. If  $y_1, y_2$  are two eigenfunctions corresponding to the same eigenvalue, then the linear combination

$$y(x) = c_1 y_1(x) + c_2 y_2(x),$$

is either an eigenfunction or a trivial solution.

3. If  $y_1$  and  $y_2$  are eigenfunctions corresponding to the same eigenvalue  $\lambda$ , then  $y_1$  and  $y_2$  are linearly dependent. Moreover

$$y_2(x)y_1'(a) - y_1(x)y_2'(a) \equiv 0.$$

4. There are only two normalized eigenfunctions for the same eigenvalue  $\lambda$ . The two differ by a multiple of  $-1$ .

**Theorem 1.** *If  $y_1$  and  $y_2$  are eigenfunctions corresponding to two distinct eigenvalues  $\lambda_1 \neq \lambda_2$ , then  $y_1$  and  $y_2$  are orthogonal to each other*

$$\int_a^b y_1(x)y_2(x)dx = 0.$$

**Theorem 2.** *All the eigenvalues for  $L$  are real.*

**Theorem 3.** *If  $\lambda$  is an eigenvalue for  $L$  and  $y$  is a normalized eigenfunction, then*

$$K[y] = \lambda.$$

**Theorem 4.** *If  $y(x)$  is an eigenfunction and if  $y_1$  is orthogonal to  $y$ , then*

$$K(y, y_1) = 0.$$

We now consider the minimization of  $K(y)$  under the condition

$$\int_1^b y^2(x)dx = 1, \quad y(a) = y(b) = 0.$$

It can be proved that there exists a  $C^1$  function  $y = y_1$  which solves the minimization problem. At some  $\lambda = \lambda_1$ , this function  $y_1$  satisfies the Euler equation (4). Therefore, for the S-L equation there exist at least one eigenvalue  $\lambda_1$  with corresponding  $y_1$ . From Theorem 3,

$$K(y_1) = \lambda_1.$$

By definition, under conditions (3), (5),  $\lambda_1$  is the minimum of  $K$  with the function  $y_1$ . By the same theorem, any other eigenvalue is also a value of  $K(y)$  with the corresponding normalized eigenfunction  $y$ . However, they are not the minimum of  $K$ . Thus,  $\lambda_1$  is the smallest eigenvalue. The fact is summarized in the following

**Theorem 5.** *The smallest eigenvalue  $\lambda_1$  is the conditional minimum of  $K$  under conditions (3) and (5).*

**Theorem 6.** *If  $\lambda_1$  is the smallest eigenvalue with eigenfunction  $y_1$ , then for any  $C^1$  function  $y(x)$  satisfying (3) and (5),*

$$K(y) \geq \lambda_1 \int_a^b y^2(x)dx.$$

*The equal sign holds iff  $y(x) = \pm ky_1$ .*

### 3. VARIATIONAL METHOD ON EIGENVALUES

Theorem 5 provides a method of getting the smallest eigenvalue  $\lambda_1$ . Other eigenvalues can also be obtained by a conditional minimization process.

**Theorem 7.** *Eigenvalues of  $L$  can be arranged as a increasing infinite sequence*

$$\lambda_1 < \lambda_2 < \cdots < \lambda_n < \cdots,$$

with corresponding eigenfunctions  $y_1, y_2, \dots$ . For each  $n$ , the eigenvalue  $\lambda_n$  is the conditional minimum of  $K(y)$  under the conditions

$$(11) \quad \int_a^b y^2 dx = 1, \int_a^b yy_i dx = 0, \quad i = 1, 2, \dots, n-1,$$

$$y(a) = y(b) = 0.$$

**Theorem 8.** For any  $C^1$  function  $y$  that is orthogonal to the first  $n-1$  eigenfunctions and satisfies (5), we have

$$(12) \quad K(y) \geq \lambda_n \int_a^b y^2 dx.$$

The equal sign happens iff  $y = ky_n$ .

**Theorem 9.** If the coefficients  $P(x)$  and  $R(x)$  increase by positive  $\delta P(x)$  and  $\delta R(x)$ , then the  $n$ th eigenvalue  $\lambda_n$ ,  $n = 1, 2, 3, \dots$  increases.

**Theorem 10.** (Courant) The  $n$ th eigenvalue, denoted  $\lambda_n(b)$  is a monotone decreasing function of the right boundary  $b$ . more over

$$\lambda_n(b) \rightarrow \infty, \quad \text{as } b \rightarrow a.$$

**Theorem 11.** (Oscillation theorem) The eigenfunction  $y_n(x)$  corresponding to the  $n$ th eigenvalue  $\lambda_n(b)$  has  $n-1$  zeros in  $(a, b)$ .

#### 4. COMPLETENESS OF THE EIGENFUNCTIONS

Let  $\{y_n\}$  be the orthonormal set of eigenfunctions corresponding to eigenvalues

$$\lambda_1 < \lambda_2 < \dots < \lambda_n < \dots$$

Then

$$\int_a^b \left( \sum_{i=1}^n a_i y_i \right)^2 dx = \sum_{i=1}^n a_i^2.$$

For any  $y \in C[a, b]$ ,  $c_i = \int_a^b yy_i dx$  is the Fourier coefficient of  $y$  with respect to  $y_i$ ,  $\sum_{i=1}^{\infty} a_i y_i(x)$  is the Fourier series for  $y(x)$  and  $\sum_{i=1}^n a_i y_i(x)$  is the partial sum. The remainder is defined as

$$R_n(x) := y(x) - \sum_{i=1}^n c_i y_i(x).$$

$$\int_a^b y^2 dx = \sum_{i=1}^n c_i^2 + \int_a^b R_n^2 dx.$$

(Parseval's inequality) 
$$\sum_{i=1}^{\infty} c_i^2 \leq \int_a^b y^2 dx.$$

If the equal sign holds for any continuous function  $y(x)$ , then we say  $\{y_n(x)\}$  is complete.

**Theorem 12.** *Eigenfunctions of the S-L equation form a complete orthonormal basis.*

*Proof.* Consider  $K(y) = \int_a^b (Py^2 + Ry^2) dx$  and its first  $n$  eigenfunctions:  $y_1, y_2, \dots, y_n$ . Let  $y(x) = \sum_1^n c_i y_i + R_n$ .

$$\begin{aligned} K(y) &= K\left(\sum_1^n c_i y_i + R_n\right) = K(R_n) + \sum_1^n c_i^2 K(y_i) \\ &\quad + 2 \sum_1^n c_i K(y_i, R_n) + 2 \sum_{i \neq j} c_i c_j K(y_i, y_j). \end{aligned}$$

Based on  $K(y_i) = \lambda_i$  and the orthogonality,

$$K(y_i, R_n) = 0, \quad K(y_i, y_j) = 0, \quad \text{if } i \neq j.$$

$$K(y) = \sum_1^n \lambda_i c_i^2 + K(R_n).$$

Since  $R_n$  is orthogonal to  $y_1, \dots, y_n$ , from Theorem 8,

$$K(R_n) \geq \lambda_{n+1} \int_a^b R_n^2 dx.$$

$\lambda_i > 0$  starting from some index  $i > i_0$ , thus,

$$K(R_n) = K(y) - \sum_1^n \lambda_i c_i^2,$$

decreases if  $n \geq i_0$ , hence bounded with respect to  $n$ .

$$\int_a^b R_n^2 dx \leq \frac{1}{\lambda_{n+1}} \left( K(y) - \sum_1^n \lambda_i c_i^2 \right).$$

Since  $\lambda_{n+1} \rightarrow \infty$ , we have

$$\lim_{n \rightarrow \infty} \int_a^b R_n^2 dx = 0.$$

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